

M-estimation for max-stable models

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Outline

- 1 Introduction to max-stable processes.
- 2 Inference problem and solutions.
- 3 Swiss rainfall.

Preliminaries

- We are interested in estimating the spatial dependence structure of extreme phenomena over a region $S \subset \mathbb{R}^2$.
- We assume an underlying stochastic process $X \equiv \{X(s)\}_{s \in S}$ that characterizes extreme spatial dependence.

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- We are interested in estimating the spatial dependence structure of extreme phenomena over a region $S \subset \mathbb{R}^2$.
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- Claim: Max-stable processes are a canonical class of models for spatial extremes.

Definition

- Let X_1, X_2, \dots be iid copies of a stochastic process $X \equiv \{X(s)\}_{s \in S}$.
- If for every n , there exists $c_n(s) > 0$ and $d_n(s)$ such that

$$\left\{ \frac{1}{c_n(s)} \bigvee_{i=1}^n X_i(s) - d_n(s) \right\}_{s \in S} \stackrel{fdd}{=} \{X(s)\}_{s \in S},$$

then X is *max-stable*.

Why max-stable?

Prop 5.9 Resnick (1987)

- Let Y_1, Y_2, \dots be iid copies of a stochastic process $Y \equiv \{Y(s)\}_{s \in S}$.
- If there exists sequence of functions $a_m(s) > 0$ and $b_m(s)$ such that

$$\left\{ \frac{1}{a_m(s)} \bigvee_{i=1}^m Y_i(s) - b_m(s) \right\}_{s \in S} \xrightarrow{fdd} \{X(s)\}_{s \in S} \quad \text{as } m \rightarrow \infty,$$

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Prop 5.10 Resnick (1987)

Concerning spatial dependence, WLOG: $\mathbb{P}[X(s) \leq x] = \exp(-1/x)$ for all $s \in S$. (standard Fréchet margins)

Characterizations of max-stable models

Finite dimensional distribution functions

Spectral representation (de Haan, 1984)

For every $D \subset S$ with $|D| = d < \infty$, there exists a *unique* finite measure H_D on $\mathbb{S}_+^{d-1} = \{u \in \mathbb{R}_+^d : \|u\| = 1\}$ such that

$$F(x) := \mathbb{P}[X(s_j) \leq x_j, j = 1, \dots, d] = \exp \left[- \int_{\mathbb{S}_+^{d-1}} \left\{ \bigvee_{j=1}^d \frac{u_j}{x_j} \right\} H_D(du) \right].$$

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- By a change of variables, a variety of flexible **parametric** max-stable models can be specified through finite dimensional distribution functions

$$F_{\theta}(x) := \exp \left[- \int_E \left\{ \bigvee_{j=1}^d \frac{g_{s_j}(w)}{x_j} \right\} \nu_{\theta}(dw) \right], \quad \theta \in \Theta \subset \mathbb{R}^p,$$

where $g_s \in \mathcal{L}_+^1(E, \mathcal{B}(E), \nu)$ for all $s \in S$.

Characterizations of max-stable models

Example: spectrally discrete

- Max-linear model:

$$F_{\theta}(x) = \exp \left[- \sum_{k=1}^K \left\{ \bigvee_{j=1}^d \frac{\theta_{jk}}{x_j} \right\} \right], \quad \theta_{jk} \geq 0.$$

- Generated by $X(s_j) = \bigvee_{k=1}^K \theta_{jk} Z_k$, where $\{Z_k\}_{k=1}^K$ iid 1-Fréchet.
- Arise naturally in economics and finance, as models of extreme losses (Einmahl et al., 2012).

Characterizations of max-stable models

Example: spectrally Gaussian

- Extremal Gaussian (Schlather, 2002):

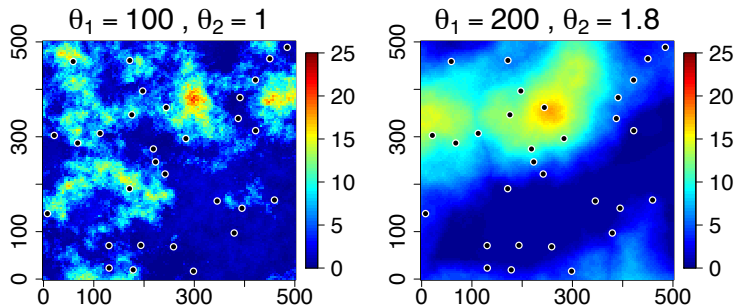
$$F_{\theta}(x) = \exp \left[- \int_{\mathbb{R}^d} \left\{ \bigvee_{j=1}^d \frac{\sqrt{2\pi} w_j \vee 0}{x_j} \right\} \phi_d(w|\theta) dw \right]$$

- $\phi_d(w|\theta)$ is a d -dim density of stationary standard Gaussian process with correlation function $\rho(\|s_i - s_j\| |\theta)$.
- Generated by $X(s_j) = \bigvee_{k=1}^{\infty} \left(\sqrt{2\pi} w_j^{(k)} \vee 0 \right) / \varepsilon_k$, $\{(w^{(k)}, \varepsilon_k)\}_{k=1}^{\infty}$ points of a Poisson point process on $\mathbb{R}^d \times \mathbb{R}_+$ with intensity measure $\phi_d(w|\theta) dw \times d\varepsilon$.

Others include well known Smith (Smith, 1990) and Brown-Resnick (Brown and Resnick, 1977) processes.

Characterizations of max-stable models

- Two realizations from extremal Gaussian with $\rho(\|s_i - s_j\|, \theta) = \exp\left[-(\|s_i - s_j\|/\theta_1)^{\theta_2}\right]$



- generated using R package `SpatialExtremes` (Ribatet, 2011).

Inference problem

- When $d > 2$, full joint likelihoods for max-stable processes are not available except in the special case of trivariate Smith models (Genton et al., 2011).

$$L_d(\theta, x) = \frac{\partial^d}{\partial x_1 \partial x_2 \cdots \partial x_d} \exp \left[- \int_E \left\{ \bigvee_{j=1}^d \frac{g_{s_j}(w)}{x_j} \right\} \nu_\theta(dw) \right] = ?$$

- Standard MLE and Bayesian inference is infeasible.
- Spawned many recent works (Padoan et al., 2010; Erhardt and Smith, 2011; Reich and Shaby, 2012; Einmahl et al., 2012).

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- (Yuen and Stoev 2013) arXiv:1307.7209 - “CDF appears natural to work with”.

Minimum distance estimation

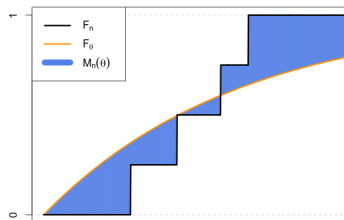
M-estimator

- Let $F_n(x) = n^{-1} \sum_{i=1}^n \mathbf{1}_{\{X_i(s_j) \leq x_j, j=1, \dots, d\}}$ - d -dim empirical CDF.
- Define

$$M_n(\theta) := \int_{\mathbb{R}_+^d} (F_n(x) - F_\theta(x))^2 \mu(dx), \quad \hat{\theta}_n := \arg \min_{\theta \in \Theta} M_n(\theta),$$

where μ is tuning measure.

- Equivalent to minimum CRPS.
- Under mild regularity, $\hat{\theta}_n$ is consistent and asymptotically normal.



Minimum distance estimation

- M-estimator is applicable to broad variety of max-stable models.
- Identifies complex tail dependence structure beyond pairwise.
- Can estimate marginal and dependence parameters together.
- Computationally expensive but dimension in 100's are possible.

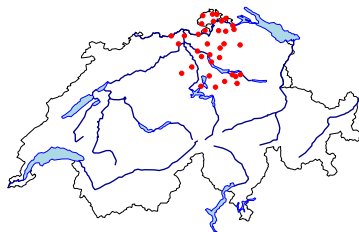
Swiss rainfall

- We model maximum single day rainfall during summer months using the extremal Gaussian model with Matérn correlation function

$$\rho(s_i, s_j | \theta) = \frac{(\|s_i - s_j\|/\theta_1)^{\theta_2}}{2^{\theta_2-1}\Gamma(\theta_2)} K_{\theta_2}(\|s_i - s_j\|/\theta_1), \quad \theta_1 > 0, \theta_2 > 0.$$

K_{θ_2} denotes the modified Bessel function of order θ_2 .

Data are recorded from 1962-2008 at 35 observation locations near Zurich, Switzerland. (Data courtesy of R package SpatialExtremes)

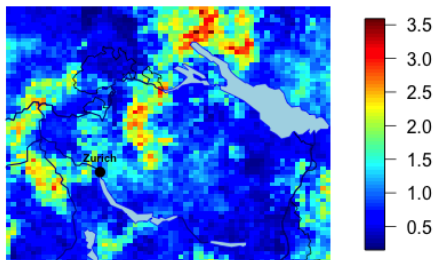
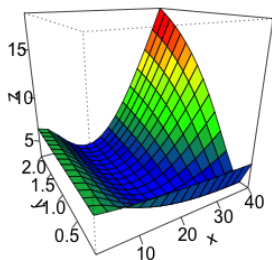


Swiss rainfall

- Summer maxima are transformed to unit Fréchet margins.
- Specifying an empirical measure for μ , we optimize the criterion $M_n(\theta)$ resulting in estimates (standard errors).

$$\hat{\theta}_1 = 18.46(25.58), \quad \hat{\theta}_2 = 0.5038(1.133).$$

- Optimization surface and one realization from the fitted model



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A.I Consistency of M-estimator

Suppose the following regularity conditions hold

- ① (Identifiability)

$$\theta_1 \neq \theta_2 \implies F_{\theta_1} \neq F_{\theta_2} \text{ a.e. } \mu.$$

- ② (Integrability) For $B(\theta_0) \subset \mathbb{R}^p$, an open neighborhood of θ_0

$$\int_{\mathbb{R}_+^d} \sup_{\theta \in B(\theta_0)} (1 - F_\theta(x)) \mu(dx) < \infty.$$

- ③ (Continuity) The function $\theta \mapsto \int_{\mathbb{R}_+^d} (F_\theta(x) - F_{\theta_0}(x))^2 \mu(dx)$ is continuous in the compact parameter space $\Theta \subset \mathbb{R}^p$.

Then $\hat{\theta}_n \xrightarrow{P} \theta_0$, as $n \rightarrow \infty$.

A.II Asymptotic normality of M-estimator

Assume the conditions above such that $\hat{\theta}_n \xrightarrow{P} \theta_0$. Suppose

- 1 The function $\theta \mapsto F_\theta(y)$ is twice continuously differentiable in an open neighborhood $B(\theta_0) \subset \mathbb{R}^p$ of θ_0 .
- 2 $\int_{\mathbb{R}_+^d} \sup_{\theta \in B(\theta_0)} \|\dot{F}_\theta(y)\| + \|\dot{F}_\theta(y)\|^2 + \|\ddot{F}_\theta(y)\| \mu(dy) < \infty$
- 3 The matrix

$$H_{\theta_0} := \int_{\mathbb{R}_+^d} \dot{F}_{\theta_0}(y) \dot{F}_{\theta_0}(y)^\top \mu(dy)$$

is nonsingular.

Then

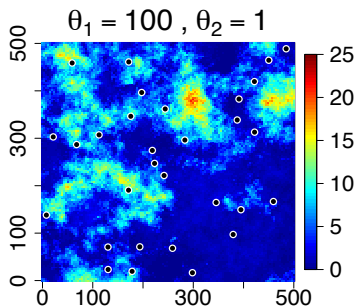
$$\sqrt{n}(\hat{\theta}_n - \theta_0) \xrightarrow{d} \mathcal{N}\left(0, H_{\theta_0}^{-1} J_{\theta_0} H_{\theta_0}^{-1}\right), \text{ as } n \rightarrow \infty,$$

$$J_{\theta_0} = \int_{\mathbb{R}_+^d} \int_{\mathbb{R}_+^d} \beta_{\theta_0}(y_1, y_2) \dot{F}_{\theta_0}(y_1) \dot{F}_{\theta_0}(y_2)^\top \mu(dy_1) \mu(dy_2) \text{ with}$$
$$\beta_{\theta_0}(y_1, y_2) = F_{\theta_0}(y_1 \wedge y_2) - F_{\theta_0}(y_1) F_{\theta_0}(y_2).$$

A.III Simulation:

Extremal Gaussian model

- 500×500 domain.
- 30 observation locations.
- 100 replications
- CI's using plug-in estimates of $H_{\theta_0}, J_{\theta_0}$.



	$\theta_1(100)$		$\theta_2(1)$	
n	100	1000	100	1000
mean	110.56	97.00	1.25	1.10
sd	113.73	32.89	0.63	0.34
.95 coverage	0.98	0.96	0.90	0.92

A.IV Marginal transformations

GEV (Fisher and Tippett, 1928; Gnedenko, 1943)

- For every $s \in S$

$$\mathbb{P}[Z(s) \leq z] = \exp \left\{ - \left[1 + \xi(s) \left(\frac{z - \mu(s)}{\sigma(s)} \right) \right]_+^{-1/\xi(s)} \right\} \quad \sigma(s) > 0.$$

- The cases $\xi(s) > 0$, $\xi(s) < 0$ and $\xi \rightarrow 0$ correspond to Fréchet, reverse Weibull and Gumbel distributions.

- Specify trend surface for parameters

$$\mu(s) = \beta_0^\mu + \beta^\mu s, \quad \sigma(s) = \beta_0^\sigma + \beta^\sigma s, \quad \xi(s) = \beta_0^\xi.$$

- Let $X(s) = [1 + \xi(s)(Z(s) - \mu(s))/\sigma(s)]^{1/\xi(s)}$
- Optimize $\int_{\mathbb{R}_+^d} (F_n(x) - F_\theta(x))^2 \mu(dx)$ over θ, β .